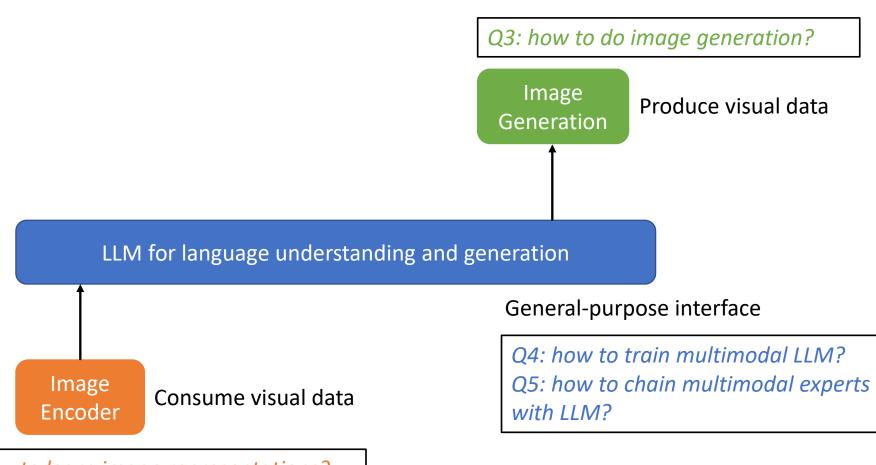




From Specialist to Generalist: Towards General Vision Understanding Interface

Jianwei Yang Microsoft Research 06/19/2023



Q1: how to learn image representations? Q2: how to extend vision models with more flexible, promptable interfaces?

Q3: how to do image generation?

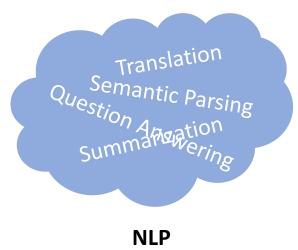
Produce visual data

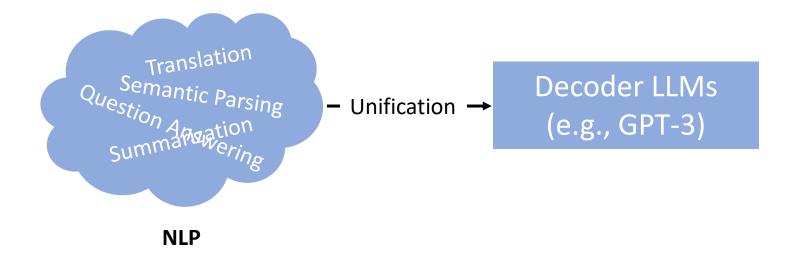
LLM for language understanding and generation

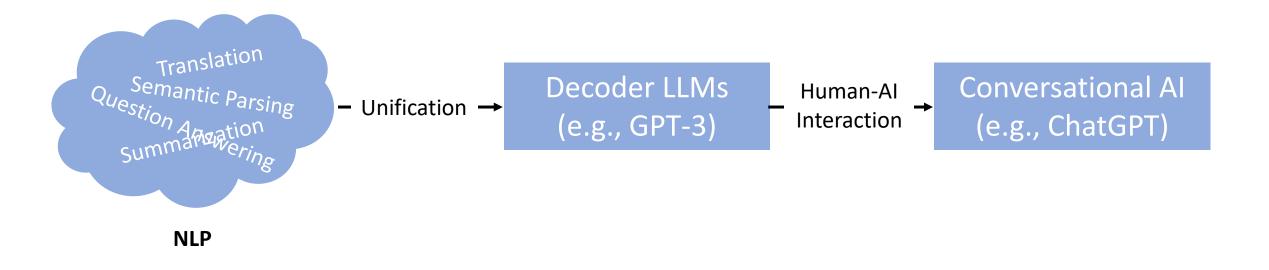
Image Encoder Consume visual data

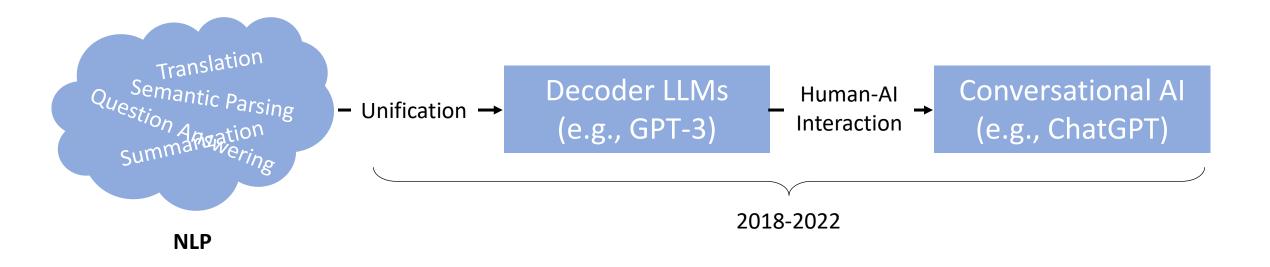
Q1: how to learn image representations? Q2: how to extend vision models with more flexible, promptable interfaces? General-purpose interface

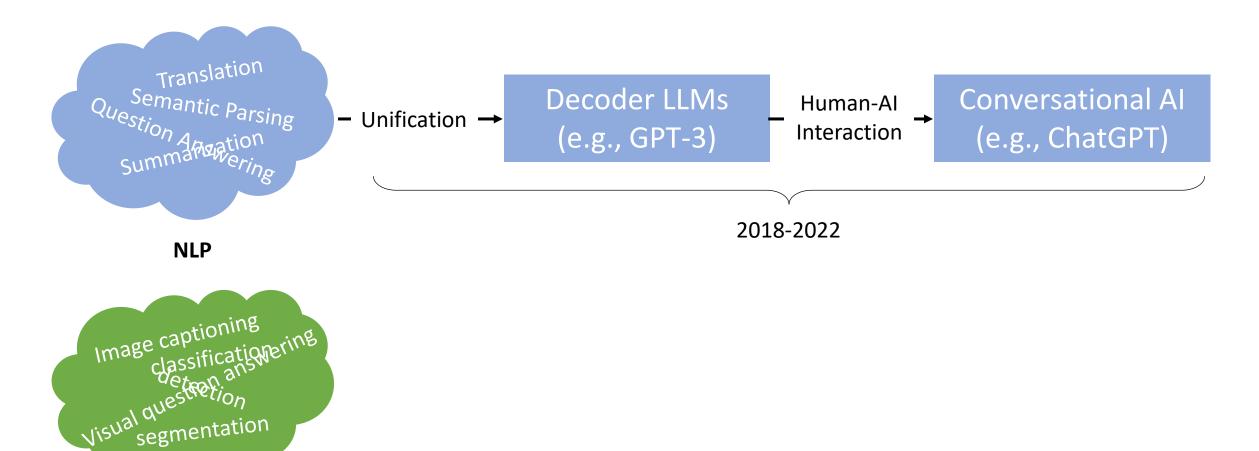
Q4: how to train multimodal LLM? Q5: how to chain multimodal experts with LLM?



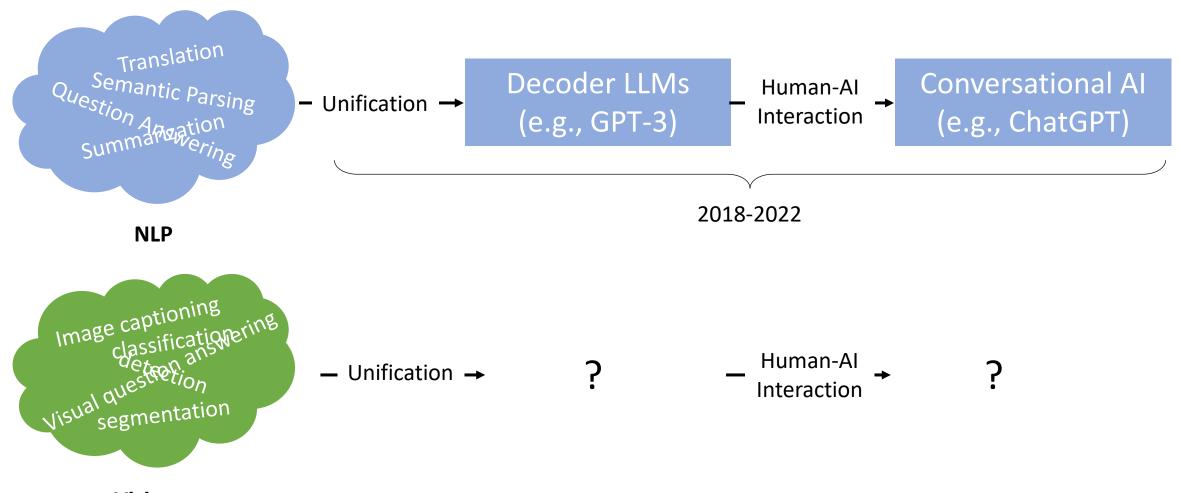




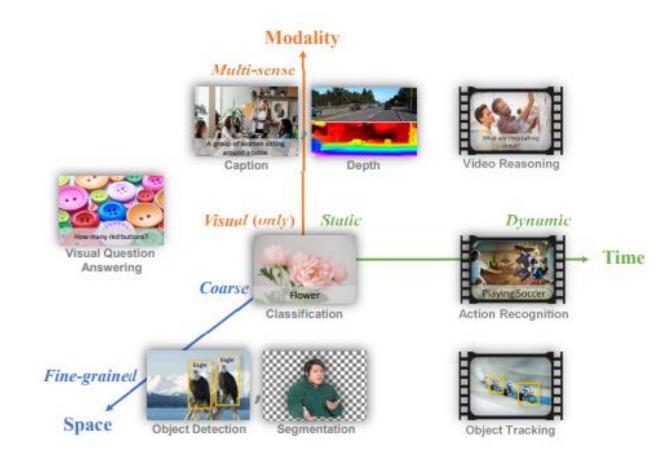




Vision

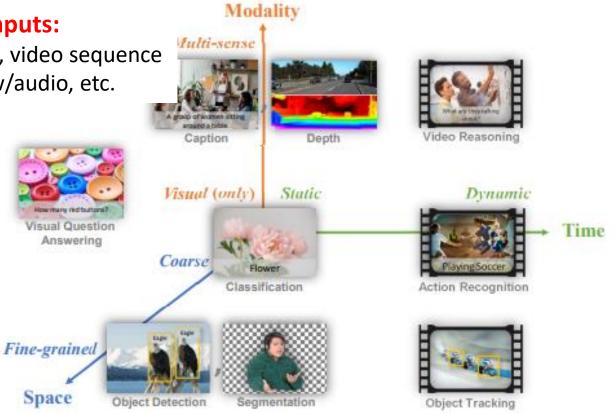


Vision



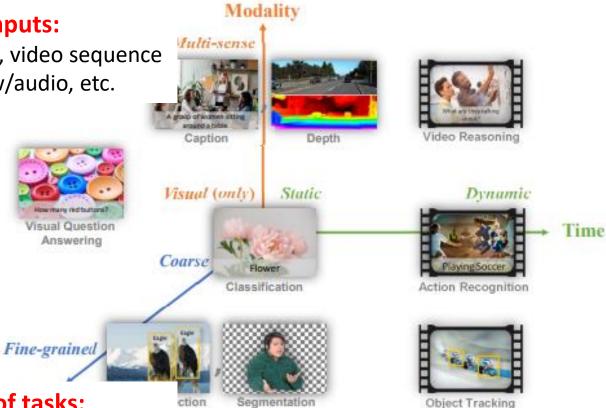
a) Different types of inputs:

<u>Temporality</u>: static image, video sequence <u>Multi-modality</u>: w/text, w/audio, etc.



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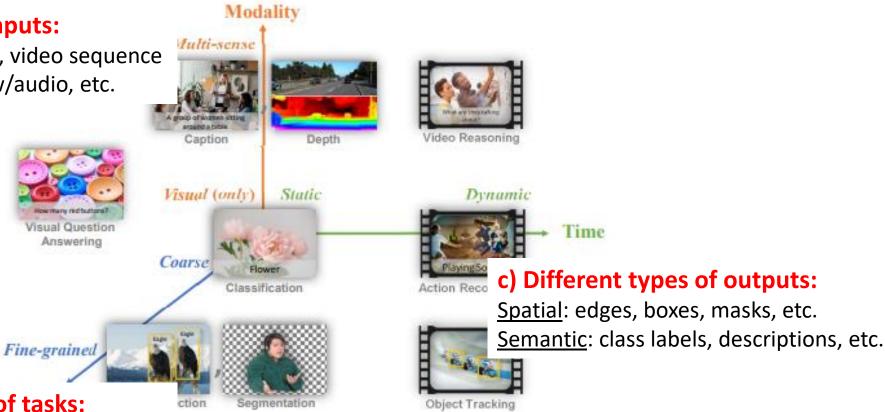


b) Different granularities of tasks:

<u>Image-level</u>: classification, captioning, etc. <u>Region-level</u>: object detection, grounding, etc. <u>Pixel-level</u>: segmentation, depth, SR, etc.

a) Different types of inputs:

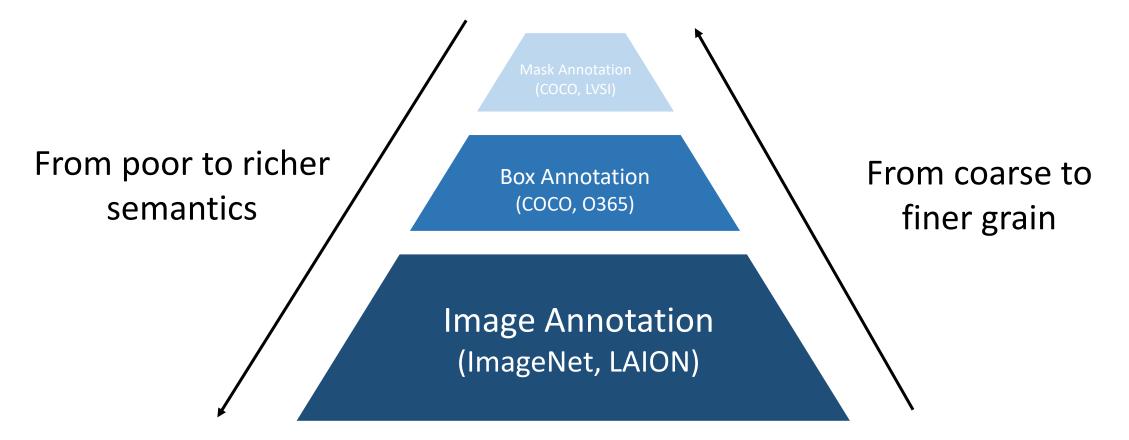
<u>Temporality</u>: static image, video sequence <u>Multi-modality</u>: w/text, w/audio, etc.



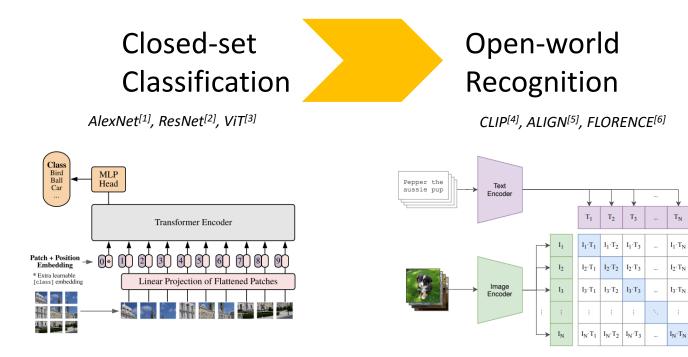
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Unique Challenges in Vision: Data



Scales differ significantly across different types of annotations

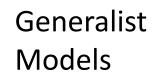


[1] Krizhevsky et al. "Imagenet classification with deep convolutional neural networks.". NeurIPS 2012

- [2] He et al. "Deep residual learning for image recognition." CVPR 2016.
- [3] Dosovitskiy et al. "An image is worth 16x16 words: Transformers for image recognition at scale." ICLR 2021.
- [4] Radford et al. Learning transferable visual models from natural language supervision, ICML 2021
- [5] Jia et al. "Scaling up visual and vision-language representation learning with noisy text supervision." ICML 2021.
- [6] Yuan et al. "Florence: A new foundation model for computer vision." arXiv 2021.

Closed-set Classification Open-world Recognition

Specialist Models



Detection^[1], Segmentation^[2], VQA^[3]

Deep ConvNet Rol projection Conv feature map Pixel2Seqv2[4], UniTAB[5], OFA[6], Unified-IO[7], X-Decoder[8]



[1] Girshick. "Fast r-cnn." CVPR 2015.

[2] He et al. "Mask r-cnn." ICCV 2017.

[3] Antol et al. "Vqa: Visual question answering." ICCV 2015.

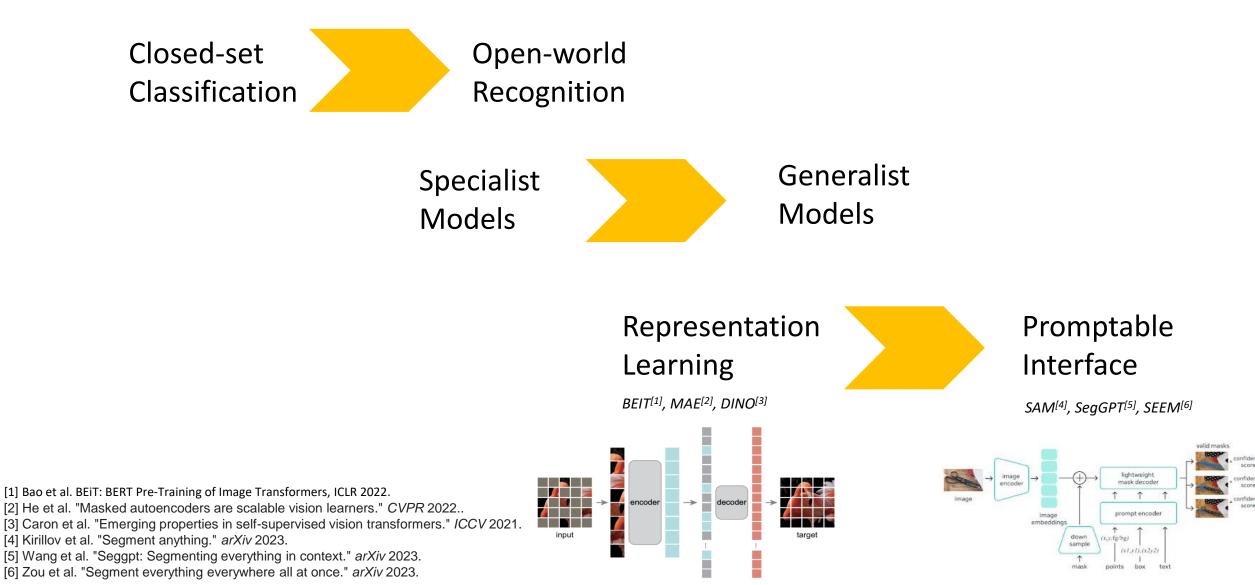
[4] Chen et al. "A unified sequence interface for vision tasks." NeurIPS 2022.

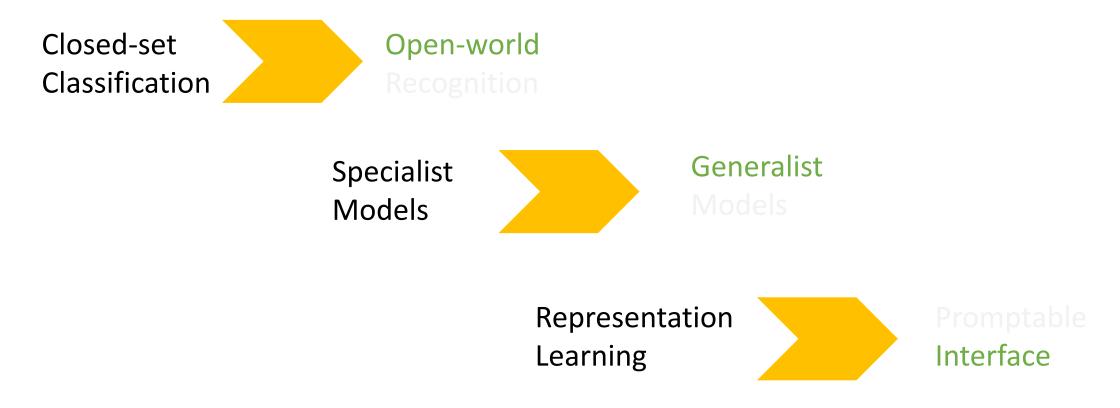
[5] Yang et al. "Unitab: Unifying text and box outputs for grounded vision-language modeling." ECCV 2022.

[6] Wang et al. "Ofa: Unifying architectures, tasks, and modalities through a simple sequence-to-sequence learning framework." ICML 2022.

[7] Lu et al. "Unified-io: A unified model for vision, language, and multi-modal tasks." ICLR 2022.

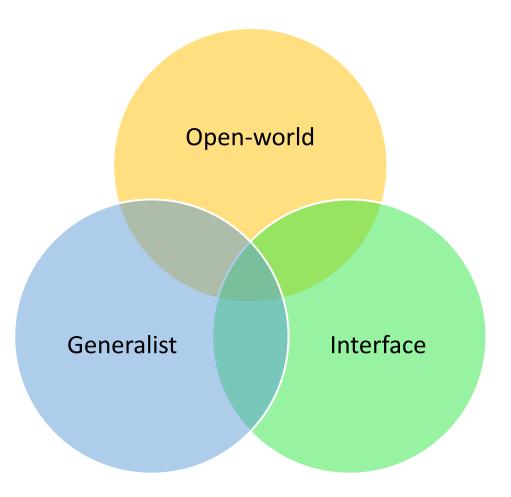
[8] Zou et al. "Generalized decoding for pixel, image, and language." CVPR 2023.



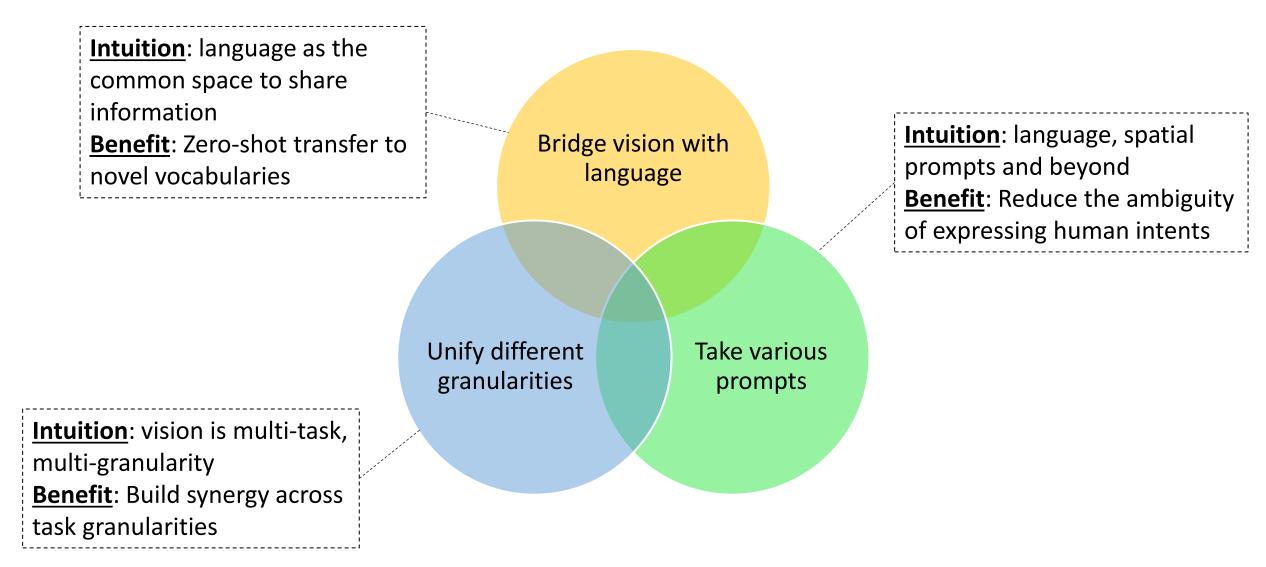


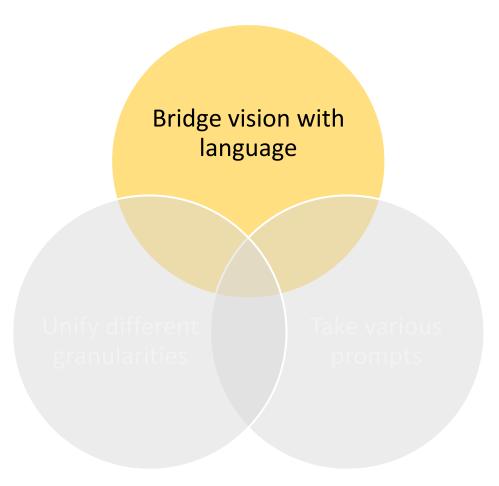
Open-worldGeneralistInterfaceRecognitionModels

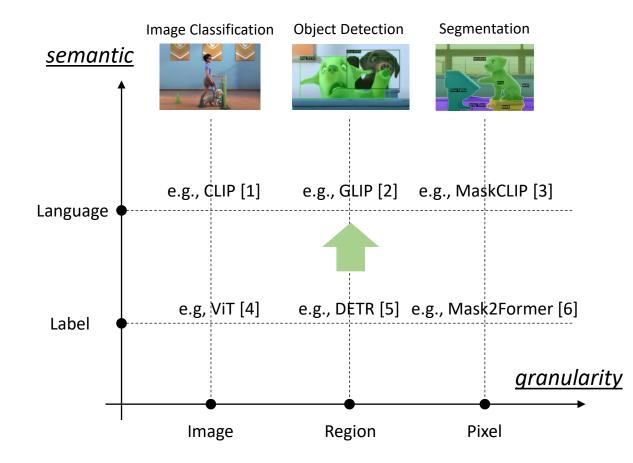
In this talk



In this talk







[1] Radford et al. "Learning transferable visual models from natural language supervision." ICML, PMLR, 2021

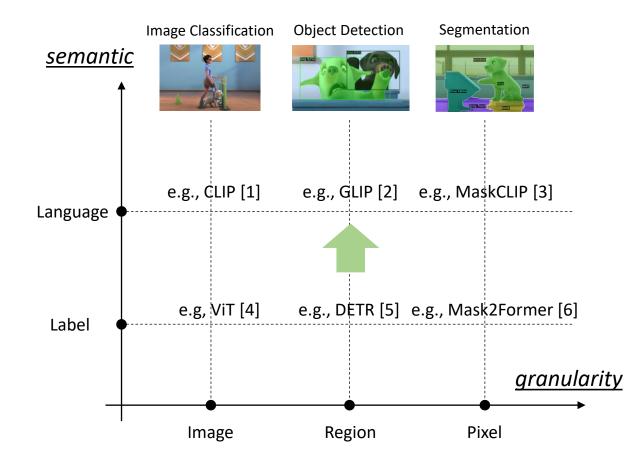
[2] Li et al. "Grounded language-image pre-training." CVPR, 2022[3] Zhou et al. "Extract Free Dense Labels from CLIP." ECCV, 2022

[4] Dosovitskiy et al. "An image is worth 16x16 words: Transformers for image recognition at scale." *ICLR*, 2021

[5] Carion et al. "End-to-end object detection with transformers." ECCV, 2020

[6] Cheng et al. "Masked-attention mask transformer for universal image

segmentation." CVPR. 2022



- (a) Converting labels to language is agnostic to granularity
- (b) Coarse-grained knowledge can be transferred to fine-grained tasks

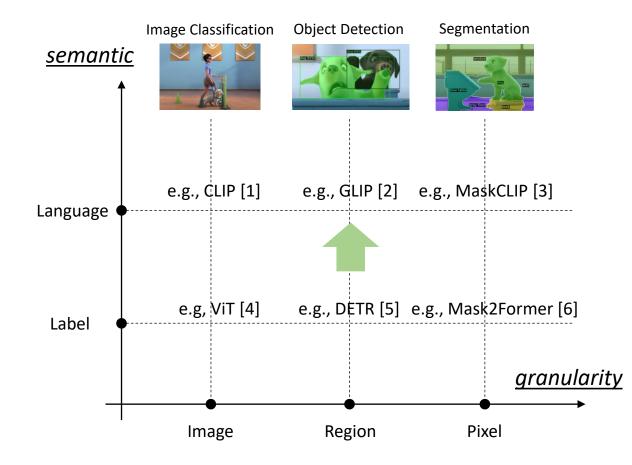
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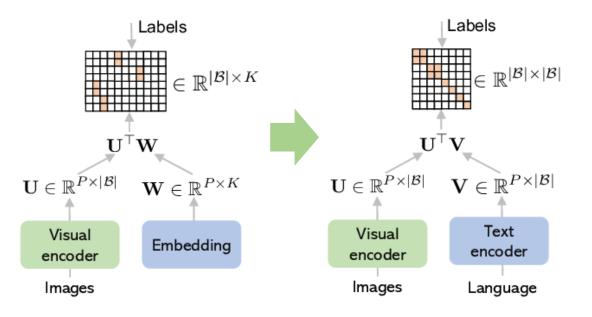
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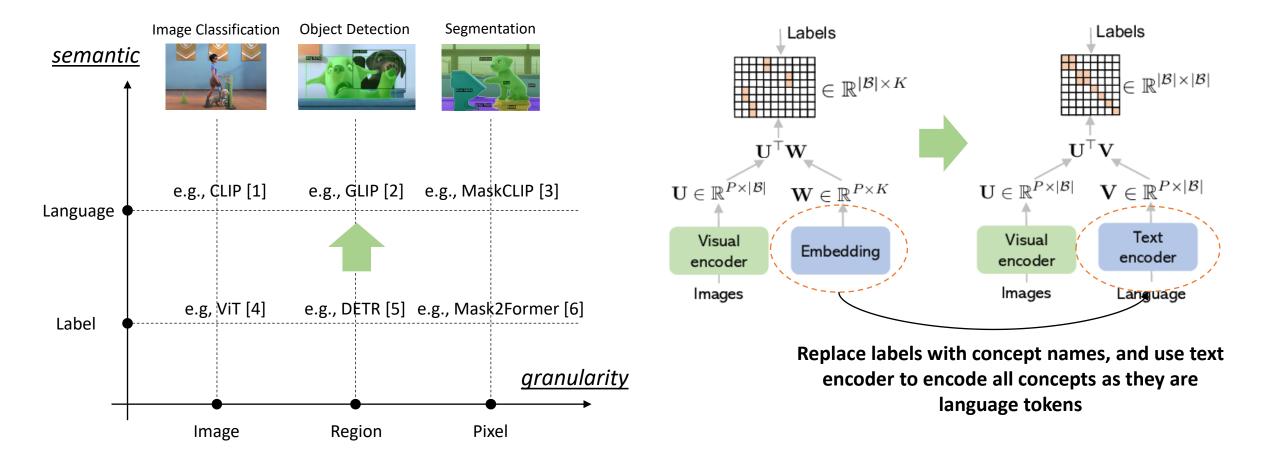
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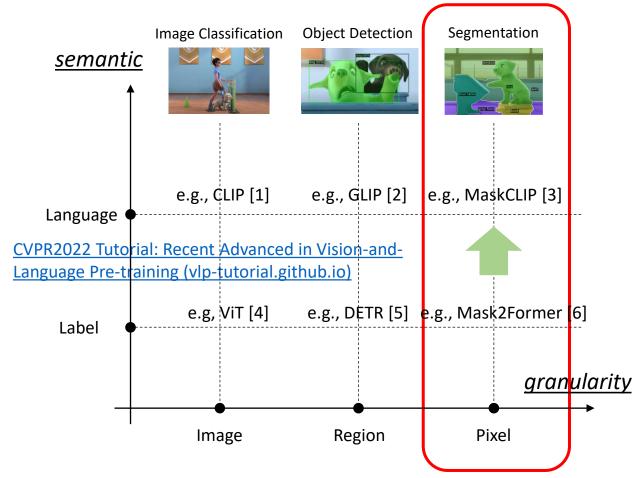
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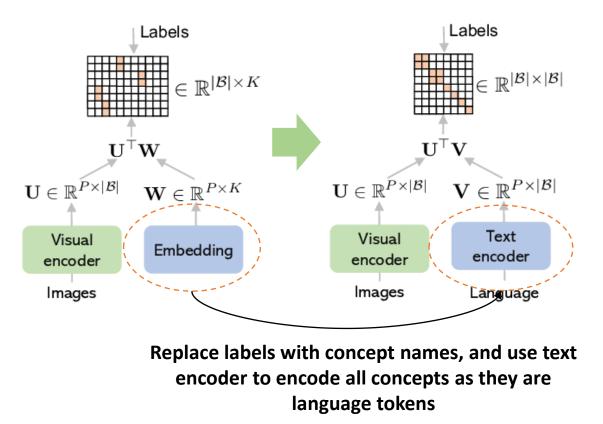
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[4] Dosovitskiy et al. "An image is worth 16x16 words: Transformers for image recognition at scale." *ICLR*, 2021

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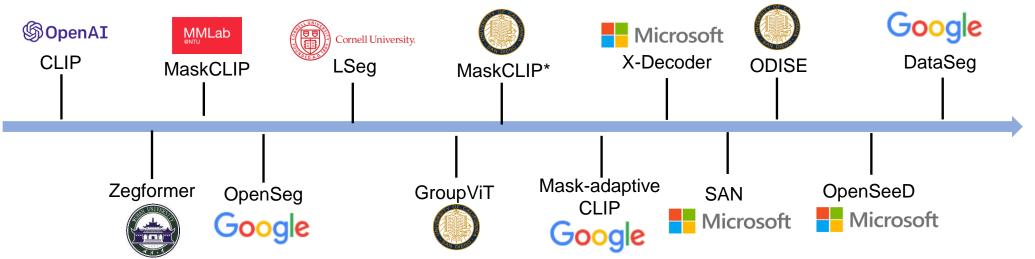
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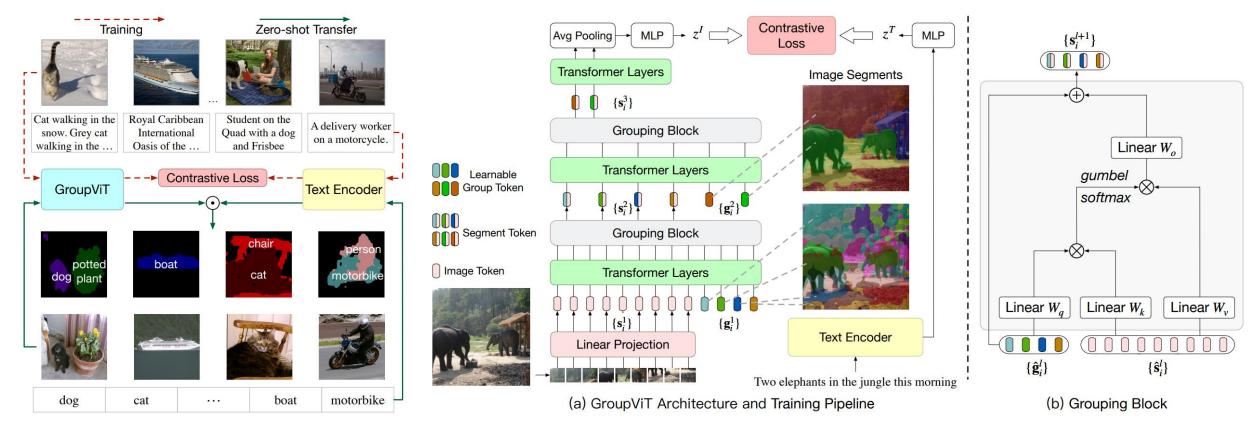
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[5] Carion et al. "End-to-end object detection with transformers." *ECCV, 2020*[6] Cheng et al. "Masked-attention mask transformer for universal image segmentation." *CVPR. 2022*

- Segmentation tasks:
 - Generic segmentation (semantic/instance/panoptic segmentation)
 - Referring segmentation (segment image with specific text phrase)
- Methodologies:
 - Initialize from CLIP v.s. train from scratch
 - Weakly supervised training v.s. supervised training
 - Two-stage v.s. end-to-end training

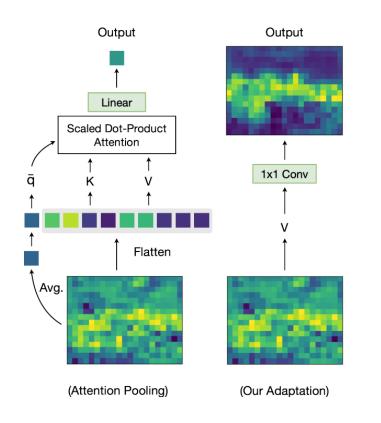


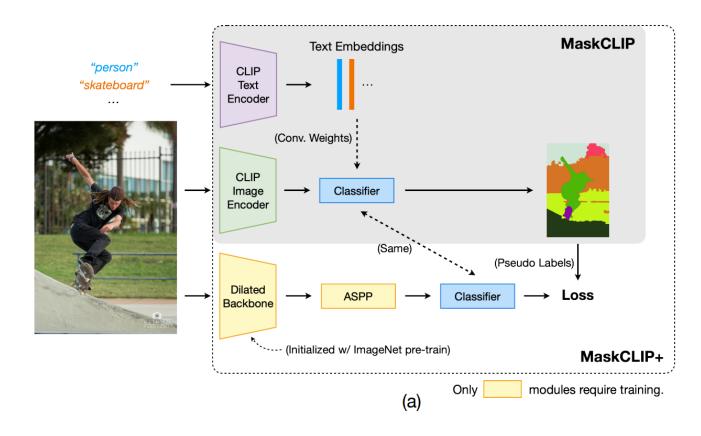
- GroupViT: Learn to group semantic similar regions by learning from image-text pairs from scratch:
 - Bottom-up grouping using a novel grouping block
 - Top-down image-text supervision for visual-semantic alignment



MaskCLIP: Extract free dense label from CLIP

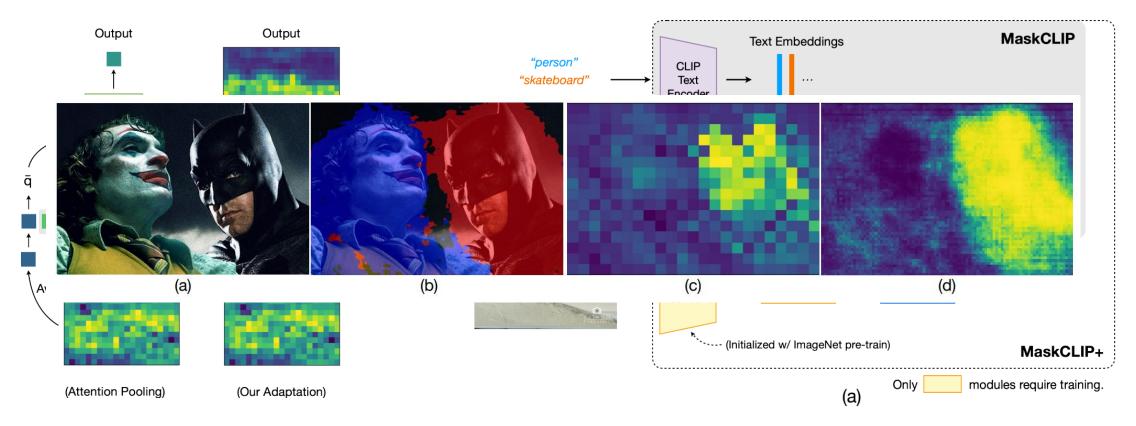
- Change attention pooling to a new adaptation strategy
- Pseudo-label masks using CLIP as the teacher model





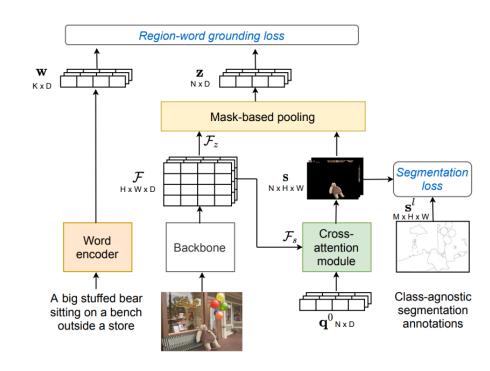
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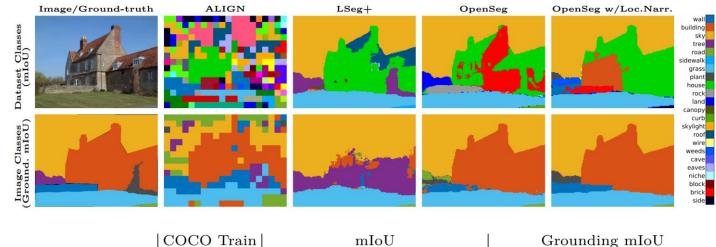
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[1] Zhou et al. "Extract Free Dense Labels from CLIP." ECCV, 2022

- OpenSeg: Weakly supervised learning by enforcing fine-grained alignment between textual features and mask-pooled features.
 - Learn from image-text pairs and local narrations.
 - A pretrained mask proposal network is used.





	CO	CO T	rain	mIoU					Grounding mIoU				
	label	mask	cap.	A-847	PC-459	A-150	PC-59	COCO	A-847	PC-459	A-150	PC-59	COCO
ALIGN	X	X	X	4.8	3.6	9.7	18.5	15.6	17.8	21.8	25.7	34.2	28.2
ALIGN w/proposal	X	1	×	5.8	4.8	12.9	22.4	17.9	17.3	19.7	25.3	32.0	23.6
LSeg+	1	1	×	3.8	7.8	18.0	46.5	55.1	10.5	17.1	30.8	56.7	60.8
OpenSeg	X	1	1	6.3	9.0	21.1	42.1	36.1	21.8	32.1	41.0	57.2	48.2
OpenSeg w/L. Narr.	X	1	1	6.8	11.2	24.8	45.9	38.1	25.4	39.0	45.5	61.5	48.2

OpenSeg w/Loc.Narr.

Grounding mIoU

25.7

25.3

30.8

41.0

39.0 45.5 61.5

34.2

32.0

56.7

57.2

21.8

19.7

17.1

32.1

idewall

gras

plan house rock

canopy curb

skylight weeds cave

eaves

niche

block

28.2

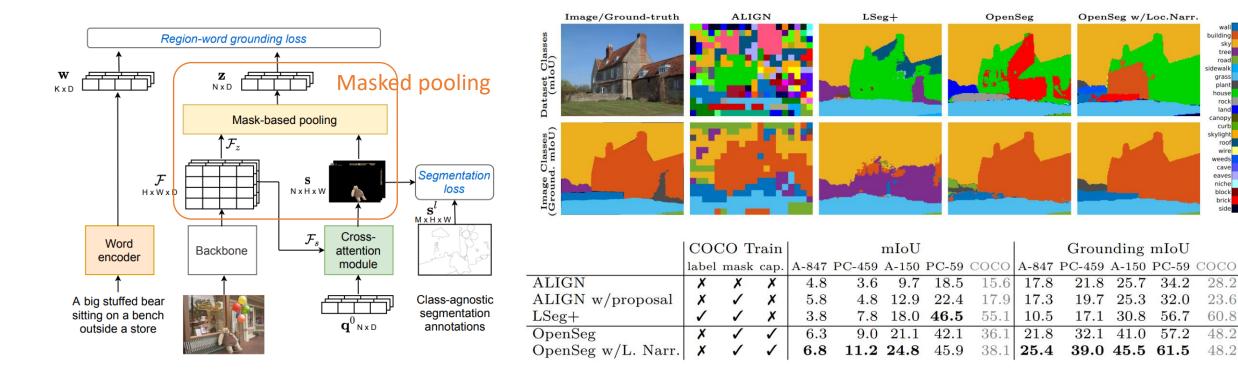
23.6

60.8

48.2

48.2

- OpenSeg: Weakly supervised learning by enforcing fine-grained alignment between textual features and mask-pooled features.
 - Learn from image-text pairs and local narrations.
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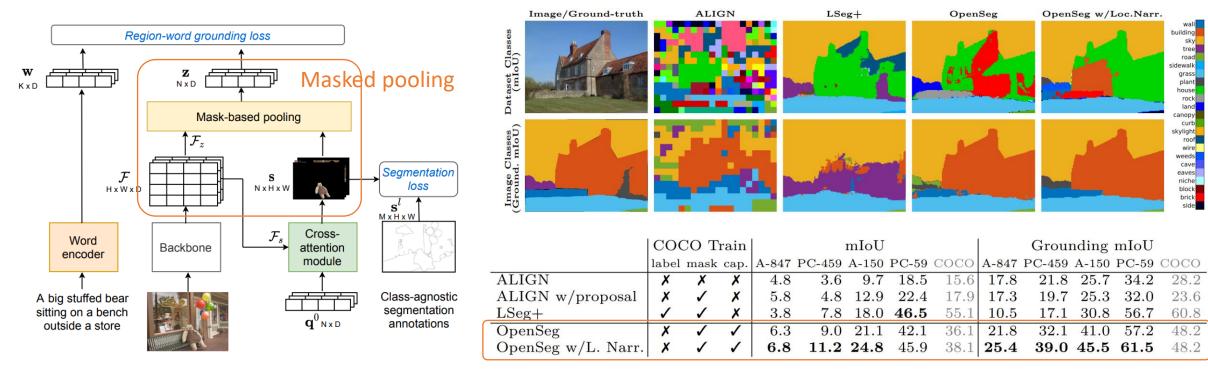
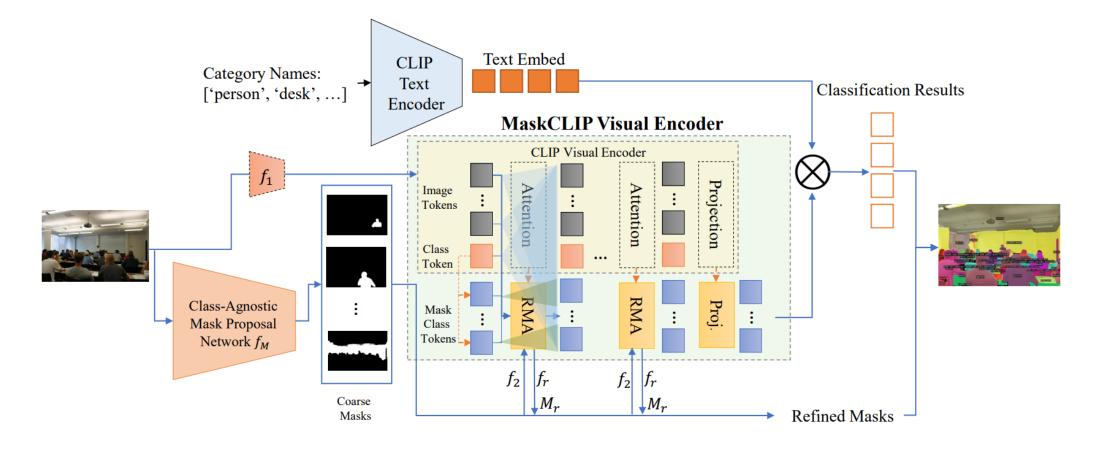


Image-text pairs helps, and local narrations further improve the performance

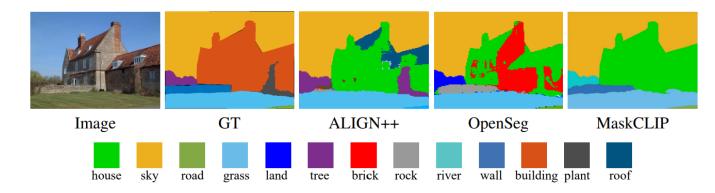
- MaskCLIP (UCSD): Supervised training for panoptic segmentation with COCO using CLIP as the initialization
 - Two-stage training: 1) mask proposal network training; 2) CLIP model adaptation



Bridge Vision with Language for Segmentation

- MaskCLIP (UCSD): Supervised training for panoptic segmentation with COCO using CLIP as the initialization
 - Two-stage training: 1) mask proposal network training; 2) CLIP model adaptation

	Method	COCO Training Data	A-150↑	A-847 ↑	P-459 ↑	P-59 ↑
	ALIGN (Jia et al., 2021)	None	10.7	4.1	3.7	15.7
	ALIGN w/ proposals (Jia et al., 2021)	Masks	12.9	5.8	4.8	22.4
	LSeg+ (Li et al., 2022a)	Masks + Labels	18.0	3.8	7.8	46.5
>	OpenSeg (Ghiasi et al., 2022)	Masks + Captions	21.1	6.3	9.0	42.1
S	SimSeg (Xu et al., 2022)	Masks + Labels	20.5	7.0	_	47.7
	CLIP Baseline	Masks	13.8	5.2	5.2	25.3
	MaskCLIP w/o RMA	Masks	14.9	5.6	5.3	26.1
	MaskCLIP (MaskRCNN)	Masks + Labels	22.4	6.8	9.1	41.3
	MaskCLIP	Masks + Labels	23.7	8.2	10.0	45.9
		•				



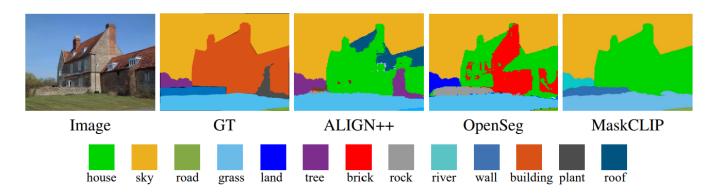
CLIP baseline works and mask proposals help slightly

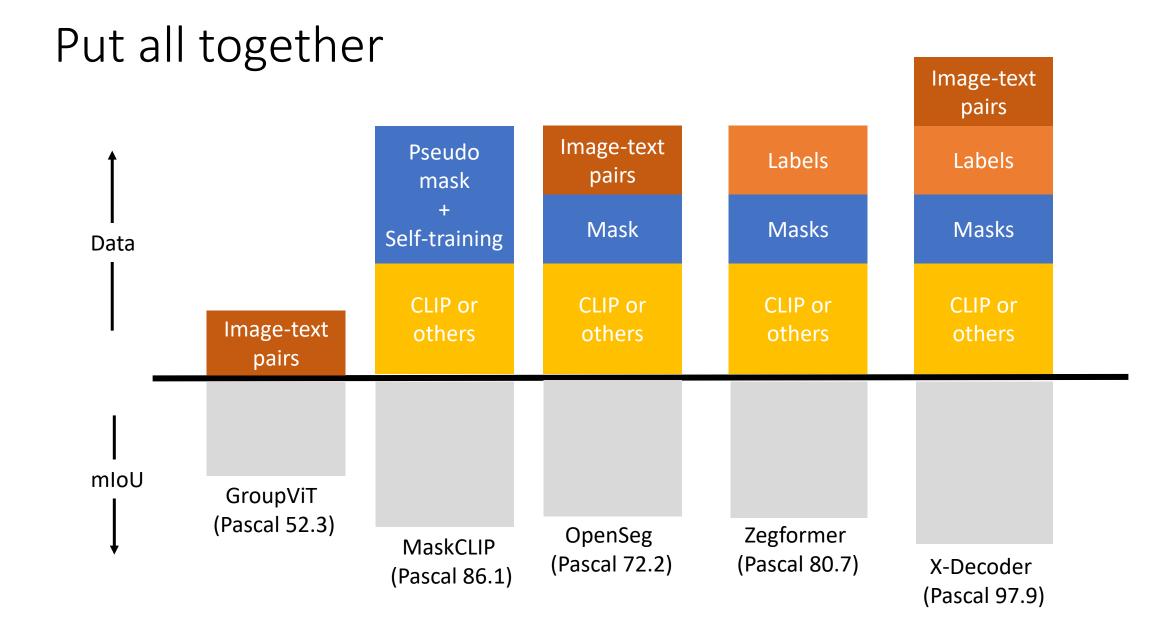
Bridge Vision with Language for Segmentation

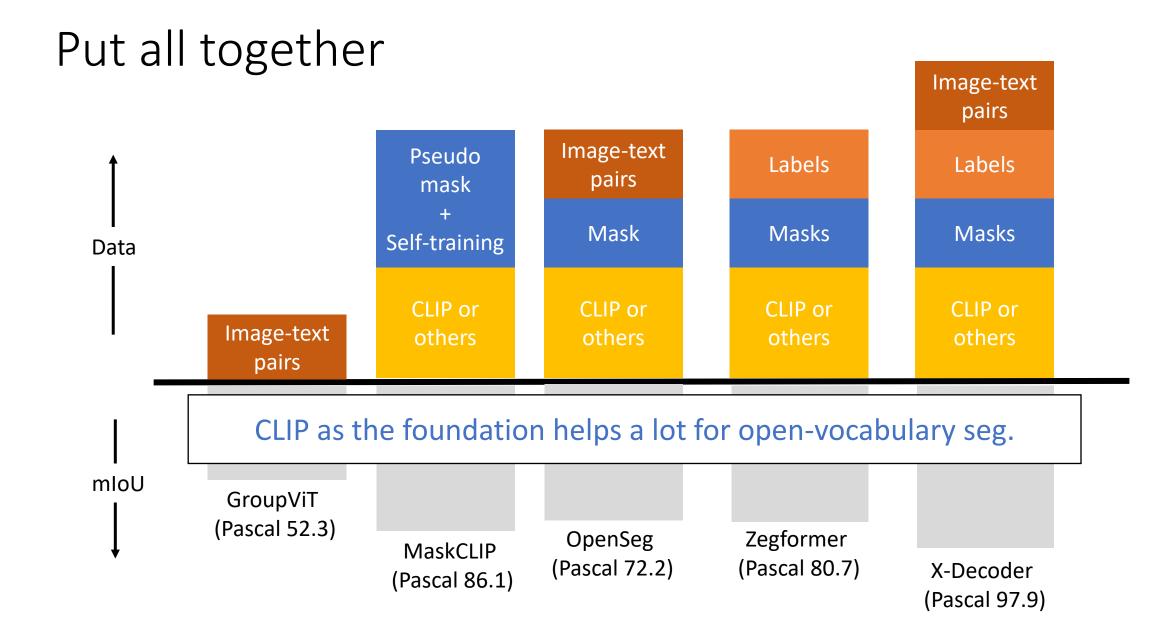
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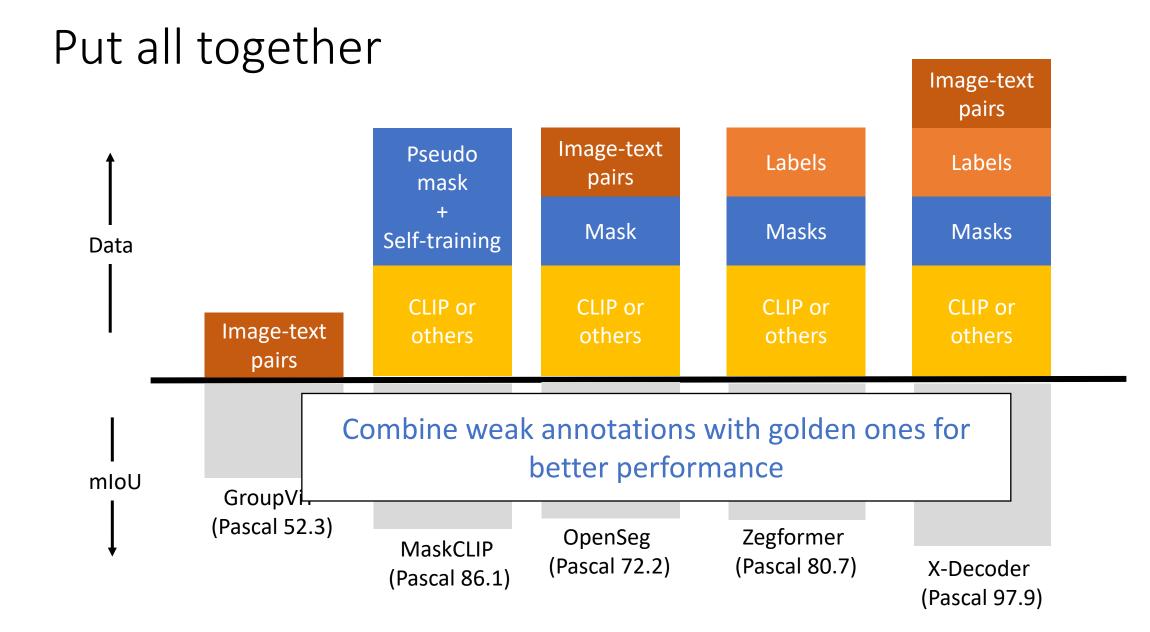
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Label information significantly boost open-vocabulary performance.

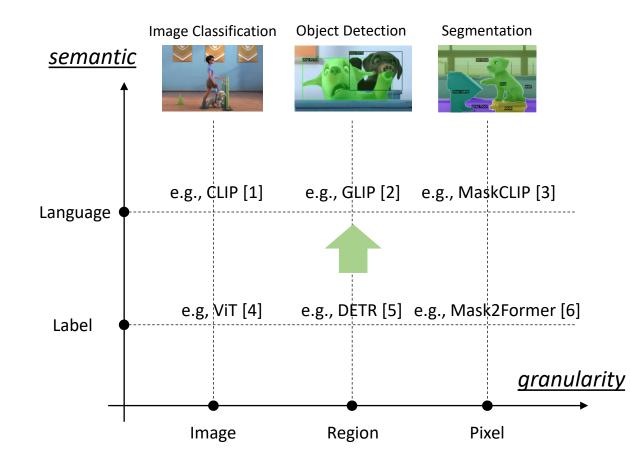




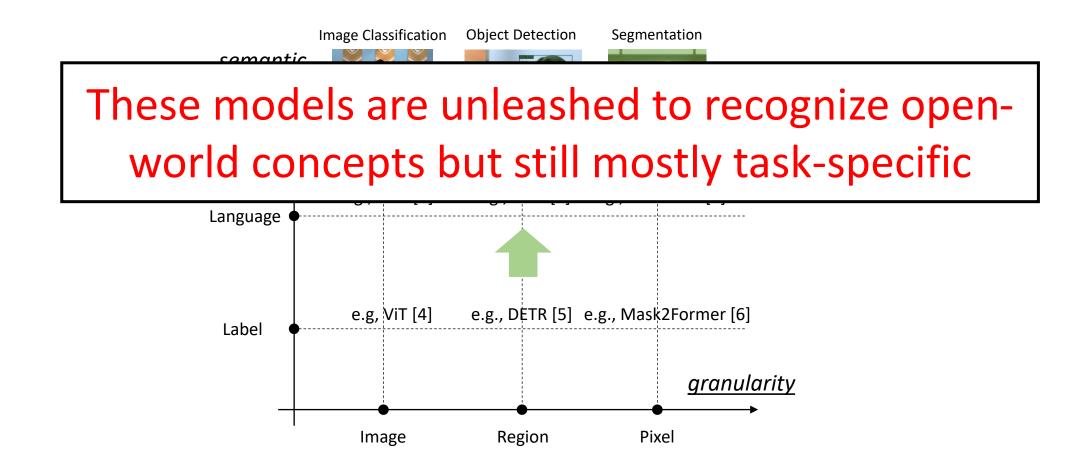




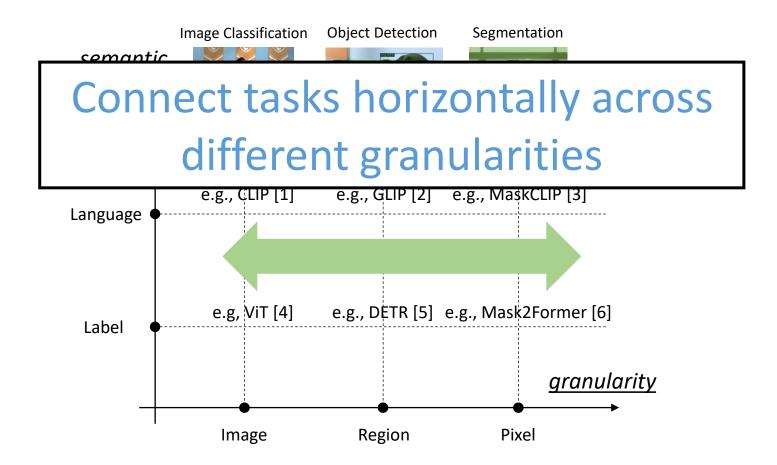
Bridge Vision with Language for Core Vision

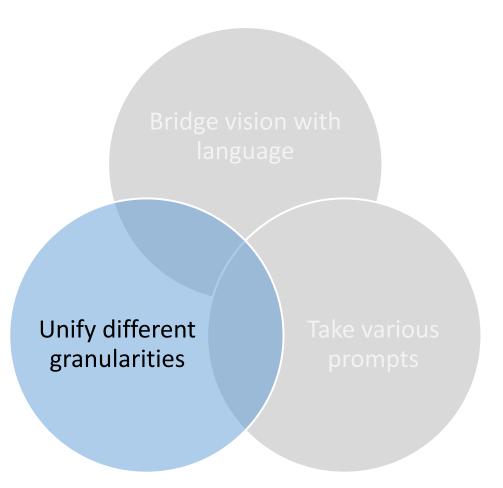


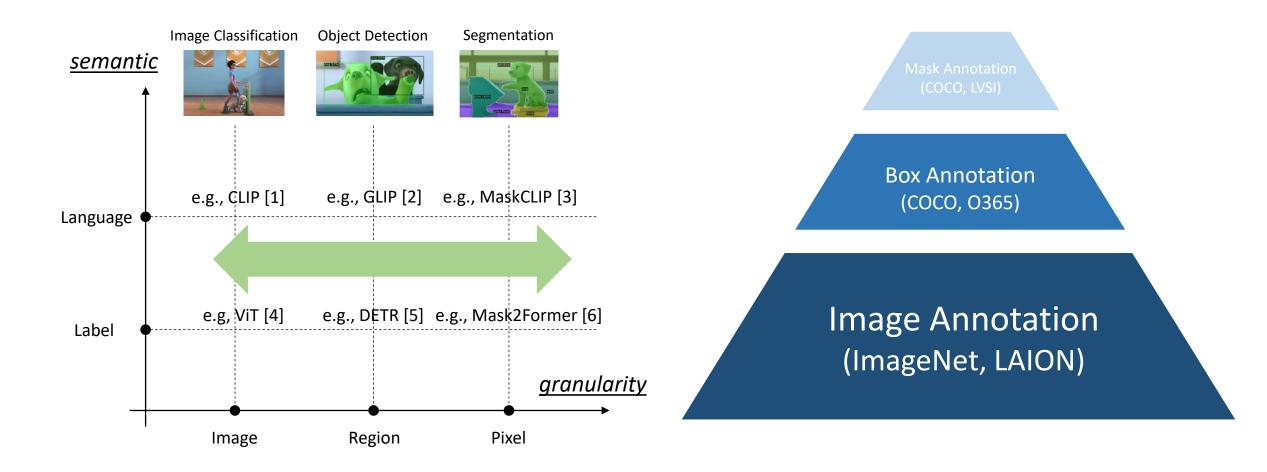
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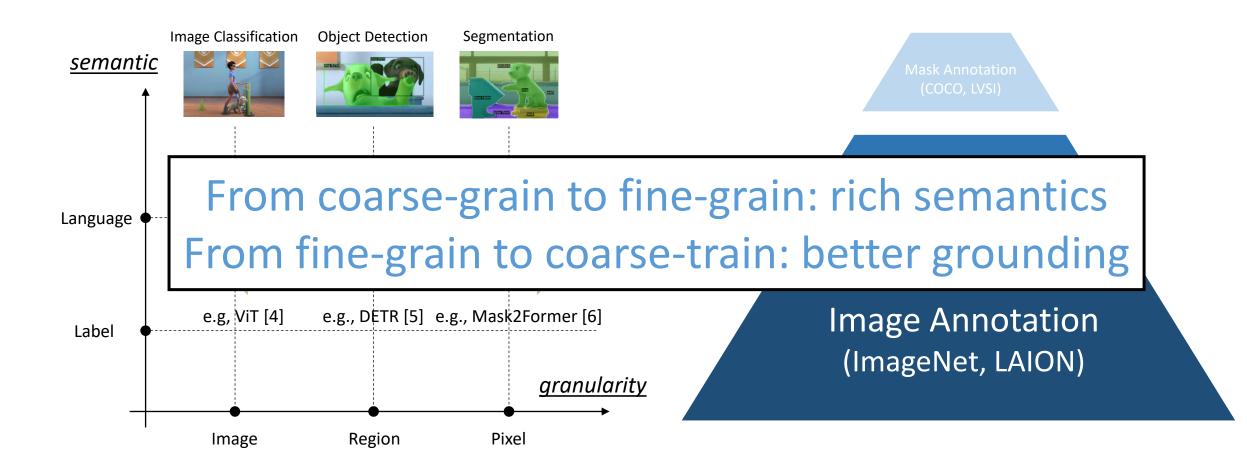


Bridge Vision with Language for Core Vision

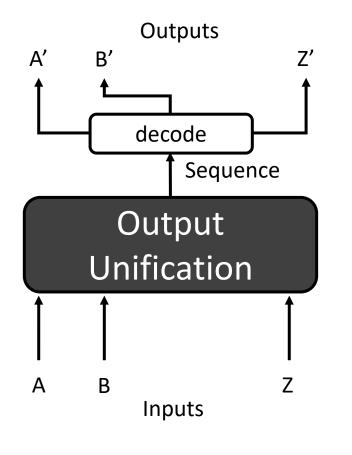




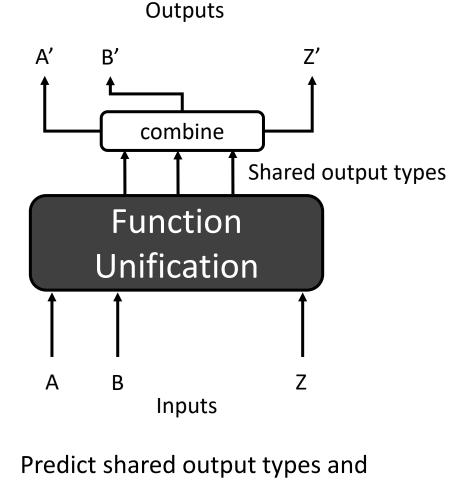




- Tasks we are considering:
 - <u>Image-level</u>: image recognition, image-text retrieval, image captioning, visual question answering, etc.
 - <u>Region-level</u>: object detection, dense caption, phrase grounding, etc.
 - <u>Pixel-level</u>: generic segmentation, referring segmentation, etc.
- Two types of unifications:
 - <u>Output unification</u>: convert all outputs into sequence.
 - <u>Functionality unification</u>: share the commons maximally but with respect to the differences.

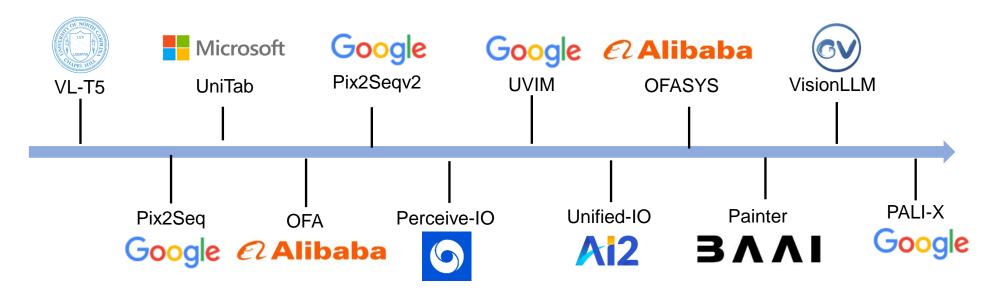


Convert all outputs into sequence and <u>decode</u> to corresponding outputs

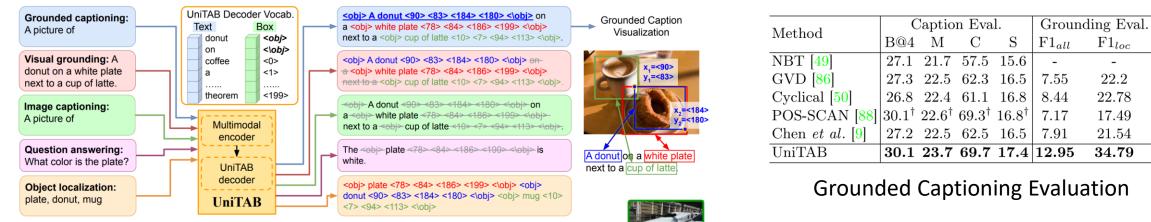


<u>combine</u> one or more to produce the final outputs

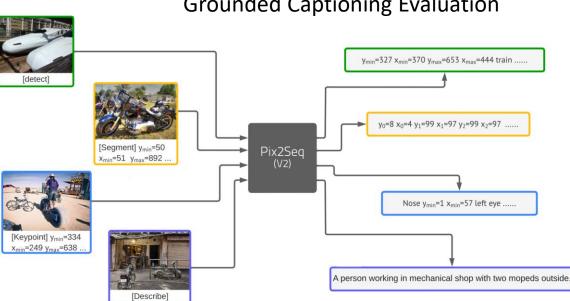
- Convert both inputs and outputs into sequences:
 - <u>Inputs</u>: Text as it is or add some prefixes; Image into a sequence of tokens (not necessarily)
 - <u>Outputs</u>: Boxes: a sequence of coordinates (top left + bottom right); Masks: a sequence of polygon coordinates encompassing mask; Key points: a sequence of coordinates.



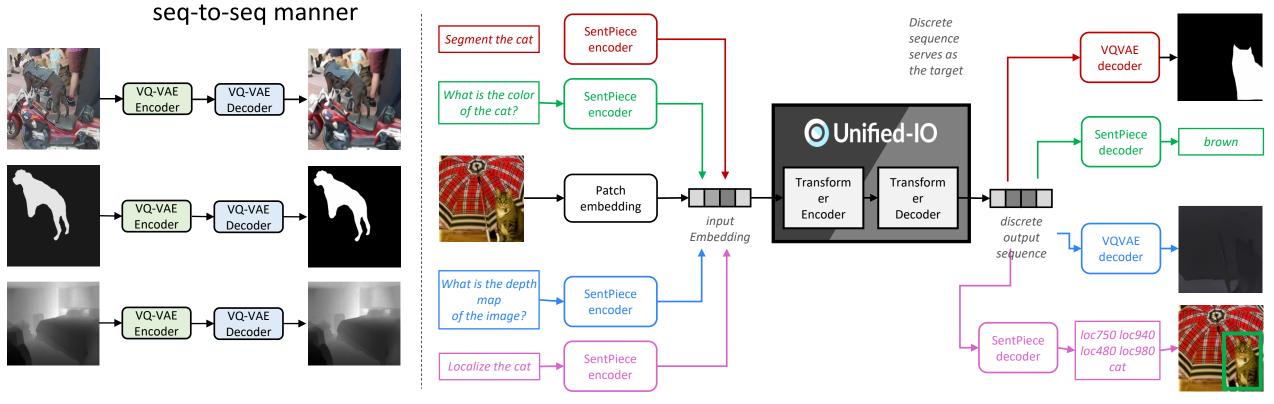
• UniTab and Pix2Seqv2: Unify text and box outputs with no specific modules



- <u>Common vocabulary</u>: text and coordinates are both tokenized and put into the same vocabulary
- <u>Task prefix</u>: requires a task prefix to determine which task the model is coping with

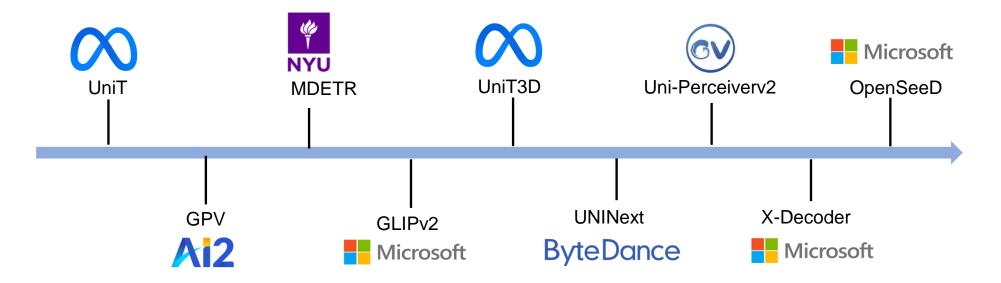


- Unified-IO: unify a wide range of understanding tasks including segmentation
 - <u>Output Quantization</u>: VQVAE for different types of tasks, such as mask, depth, image. (shared by UViM and OFA to some extent)
 - <u>Two-stage pretraining</u>: 1) pretraining VQVAE; 2) jointly pretraining on multiple tasks in a



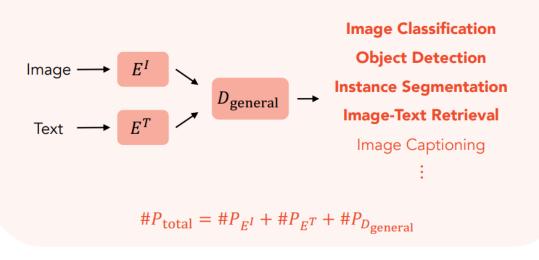
- Other works like VisionLLM use LLM as the output interface
- It unifies a wide range of vision tasks so that an encoder-decoder can be trained end-to-end
- It also:
 - needs task-specific decoder to decode the sequence to final outputs:
 - E.g., extract coordinates and translate into a box, convert polygon/color map into mask
 - might be hard to interpret the interactions across different tasks of different granularities
 - may not be able to build a strong cross-task synergy as we expect

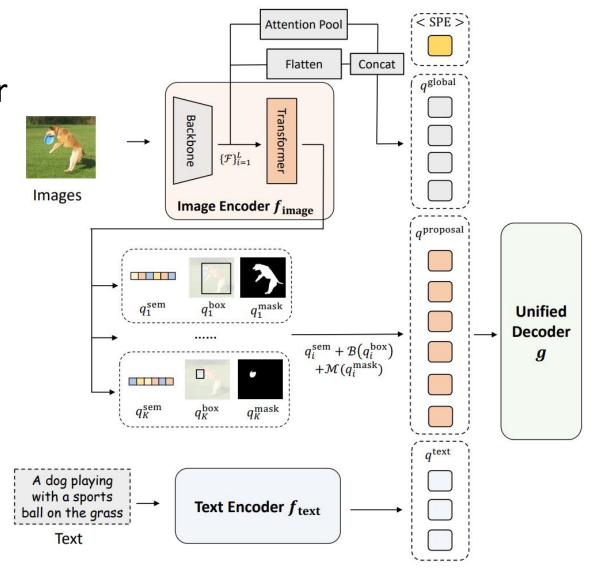
- Vision tasks are not fully isolated:
 - Box outputs: shared by generic object detection, phrase grounding, regional captioning
 - <u>Mask outputs</u>: shared by instance/semantic/panoptic segmentation, referring segmentation, exemplar-based segmentation, etc.
 - <u>Semantic outputs</u>: shared by image classification, image captioning, regional captioning, detection, segmentation, visual question answering, image-text retrieval, etc.



 UniPerceiver-v2: a unified decoder is exploited for many vision understanding tasks

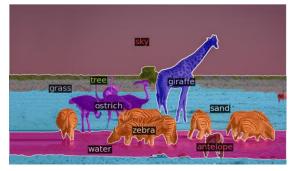
Our Generalist Model – Uni-Perceiver v2 General Task Adaptation





• X-Decoder: Generalized Decoding for Pixels, Images, and Language

• X-Decoder: Generalized Decoding for Pixels, Images, and Language



Query:Zebra,antelope,giraffe,o strich, sky, water, grass, sand, tree



Query: Owl on the left



Query: The tangerine on the



Cap: river in the mountains near the town

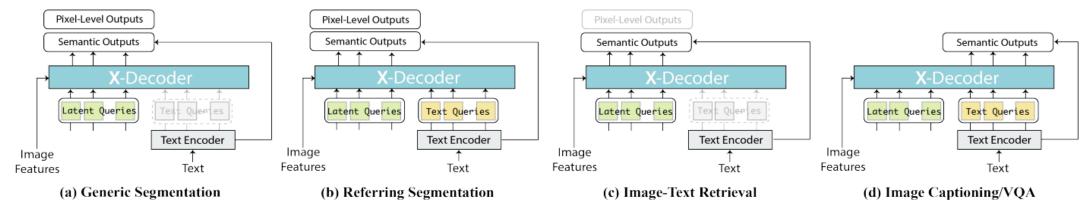
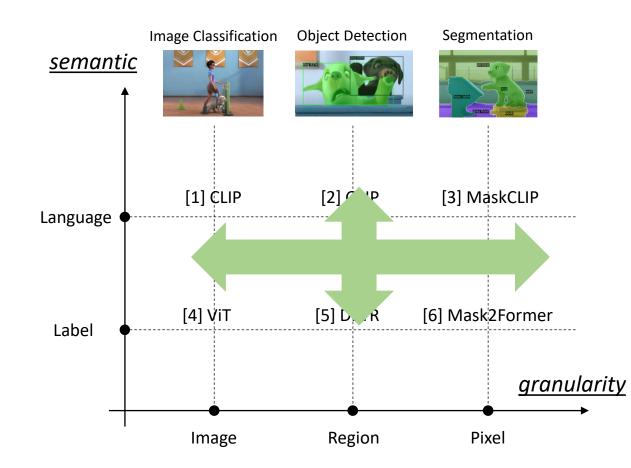


plate.



Computer Vision in the Wild



Image Classification in the Wild

Example of knowledge sources



Concept name: risotto

with rice and other ingredients
Def_wn: rice cooked with broth and sprinkled with grated cheese

Def_wik: An Italian savoury dish made

Path_wn: [risotto, dish, nutriment, food, substance, matter, physical_entity, entity]

GPT3: ["A rice dish made with arborio rice and typically served with meat or fish.", "A rice dish made by stirring rice into a simmering broth]



Object Detection in the Wild

Example of knowledge sources



Concept name: starfish

Def_wik: Any of various asteroids or other echinoderms (not in fact fish) with usually five arms, many of which eat bivalves or corals by everting their stomach.

NORMET Def_wn: echinoderms characterized by five arms extending from a central disk

Path_wn: [starfish, echinoderm, invertebrate, animal, organism, living_thing, whole, object, physical_entity, entity]

GPT3: A marine animal of class Asteroidea, typically having a central disk and five arms.



Segmentation in the Wild

Exemplar images in SGinW Benchmark

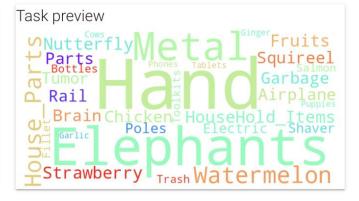


Task preview

Flowers102 DTD Food101 Country211 RESISC45 FGVCAircraft Caltech101 FER2013KittiDistanceEuroSatVOC2007 StanfordCars MNIST GTSRB OxfordPetsCIFAR100CIFAR10

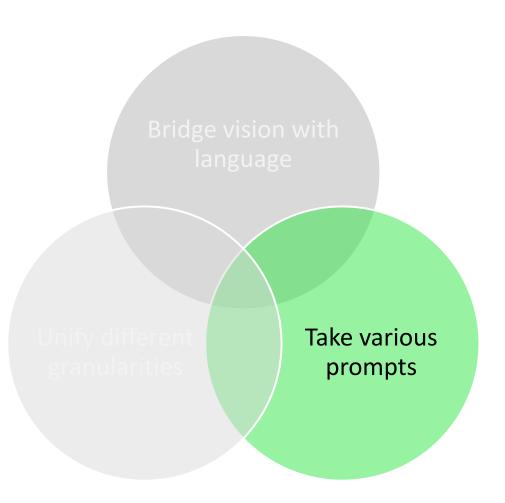
Task preview

ChessPieces Packages Packages PascalVOC PKLot640 OpenPoetryVision PerialMaritimeDrone(large) Pistols Plantdoc Raccoon Aquarium Dice BoggleBoards ThermalDogSAndPeople AmericanSignLanguageLetters ThermalChestah UnoCards VehiclesOpenImages DroneControl SelfDrivingCar OxfordPets(breed) EgoHands(specific) AerialMaritimeDrone(tiled)EgoHands(generic)

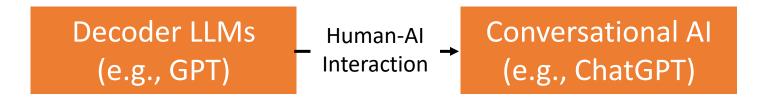


2nd Workshop on Computer Vision in the Wild, East Ballroom B, June 19th full day

Promptable Interface



How to Enable Vision Model to "Chat"





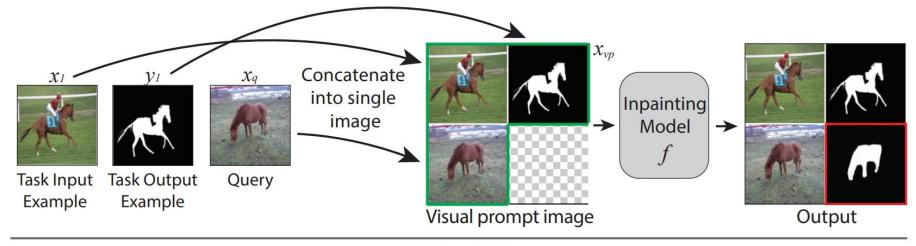
How to Enable Vision Model to "Chat"

- We need to build a promptable interface with two important properties:
 - <u>Promptable for in-context learning</u>: Instead of finetuning the model parameters, simply providing some contexts will make the model precit
 - Interactive for user-friendly interface: multi-round of interaction between human and AI is important to finish complicated tasks.

In-Context Learning for Vision

• Visual Prompting via Image Inpainting:

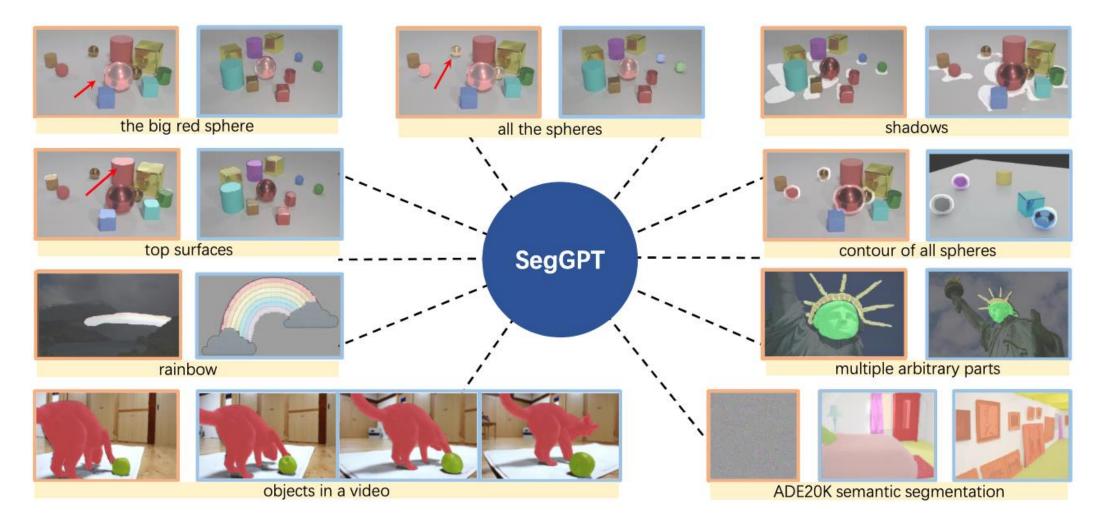
- Concatenate in-context sample with query into a single image
- Ask model to inpaint the missed part of the image grid



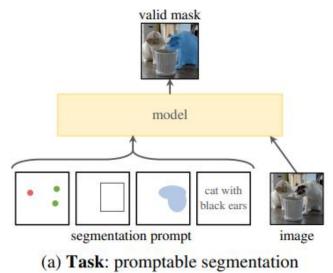


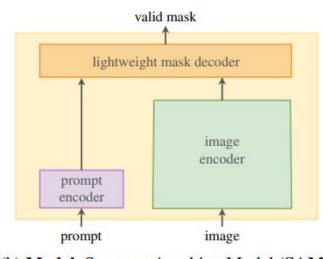
In-Context Learning for Vision

• SegGPT: Segment Everything as in-context learning

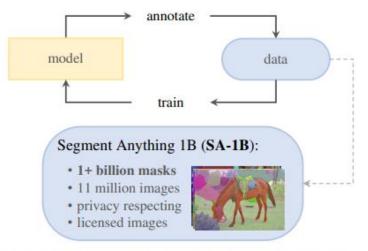


- SAM: Segment Anything
 - Promptable segmentation

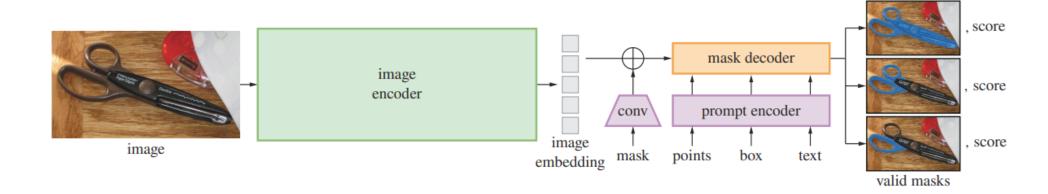




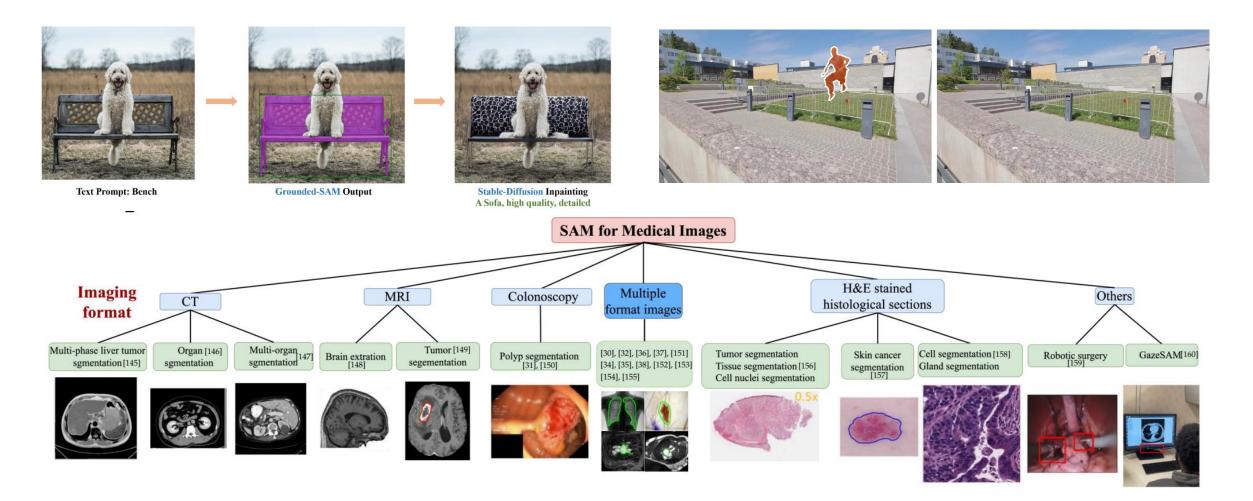
(b) Model: Segment Anything Model (SAM)



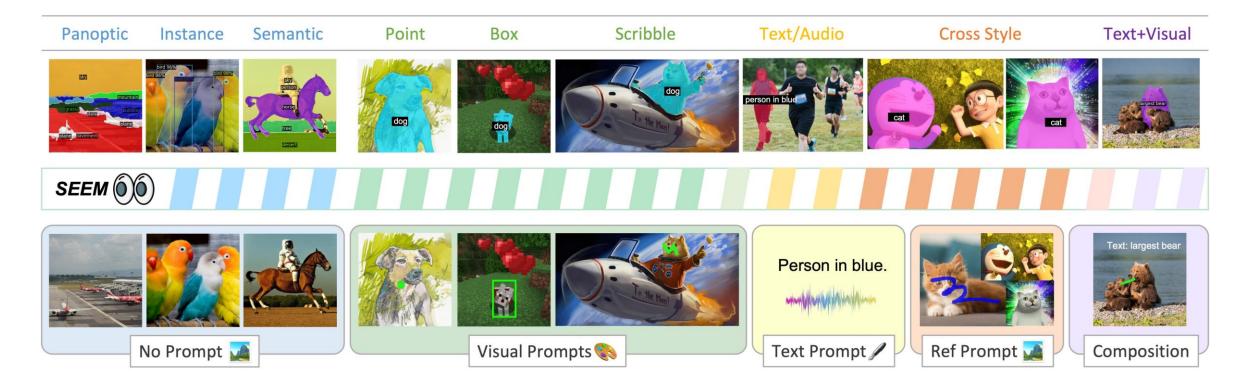
(c) Data: data engine (top) & dataset (bottom)



• SAM: Segment Anything



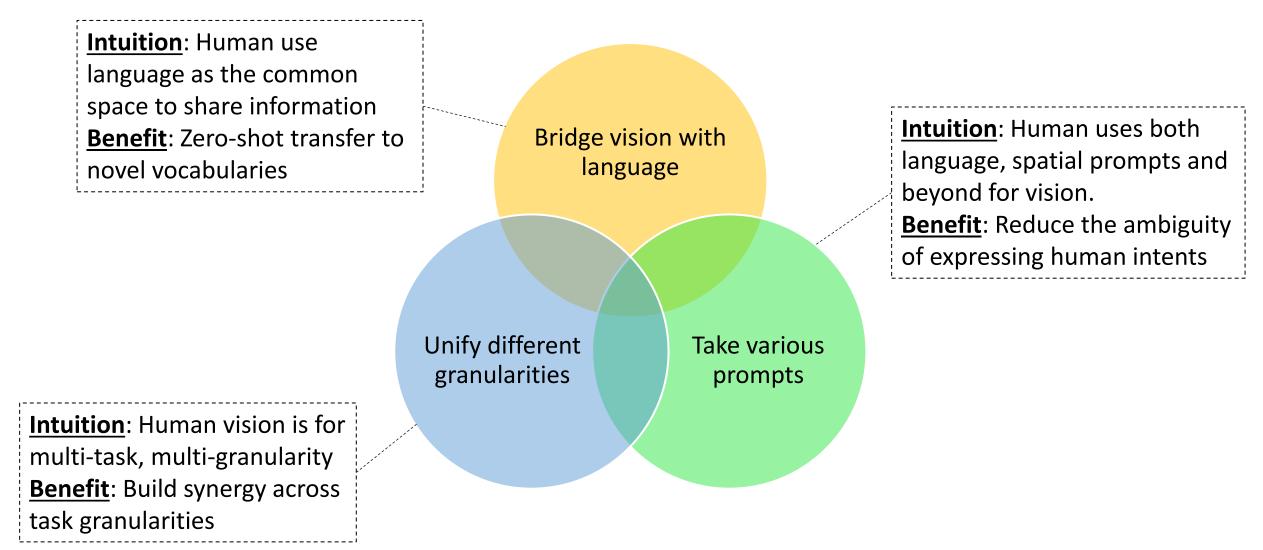
• **SEEM**: Segment Everything Everywhere all at Once



• **SEEM**: Segment Everything Everywhere all at Once



A quick recap

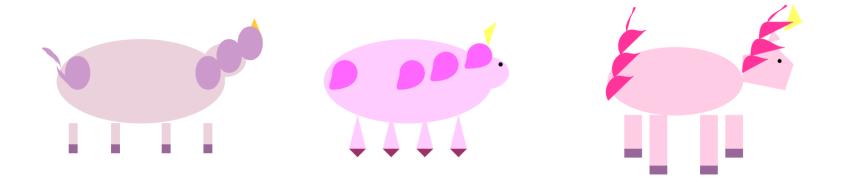


Sparks of Artificial General Intelligence (AGI)

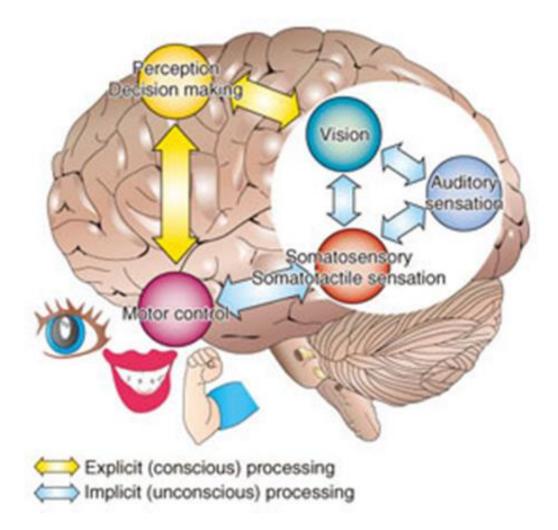
Sparks of Artificial General Intelligence: Early experiments with GPT-4

Sébastien BubeckVarun ChandrasekaranRonen EldanJohannes GehrkeEric HorvitzEce KamarPeter LeeYin Tat LeeYuanzhi LiScott LundbergHarsha NoriHamid PalangiMarco Tulio RibeiroYi Zhang

Microsoft Research



Artificial General Intelligence (AGI)



- Natural Language Processing
- Computer Vision

. . .

- Auditory sensation Speech
- Motor control Action

Drawing dots for generalist vision to



Enable an intimate cooperation with LLMs for physic world task Give GPT, ChatGPT, BioGPT the eyes!

Empower more grounded image/video manipulation

Let DALLE-1/2 not only imaging things but grounding to the realistic! Achieve multi-sensory general intelligent agent!

A real agent that can see, talk, act!

Thanks for your attention!